

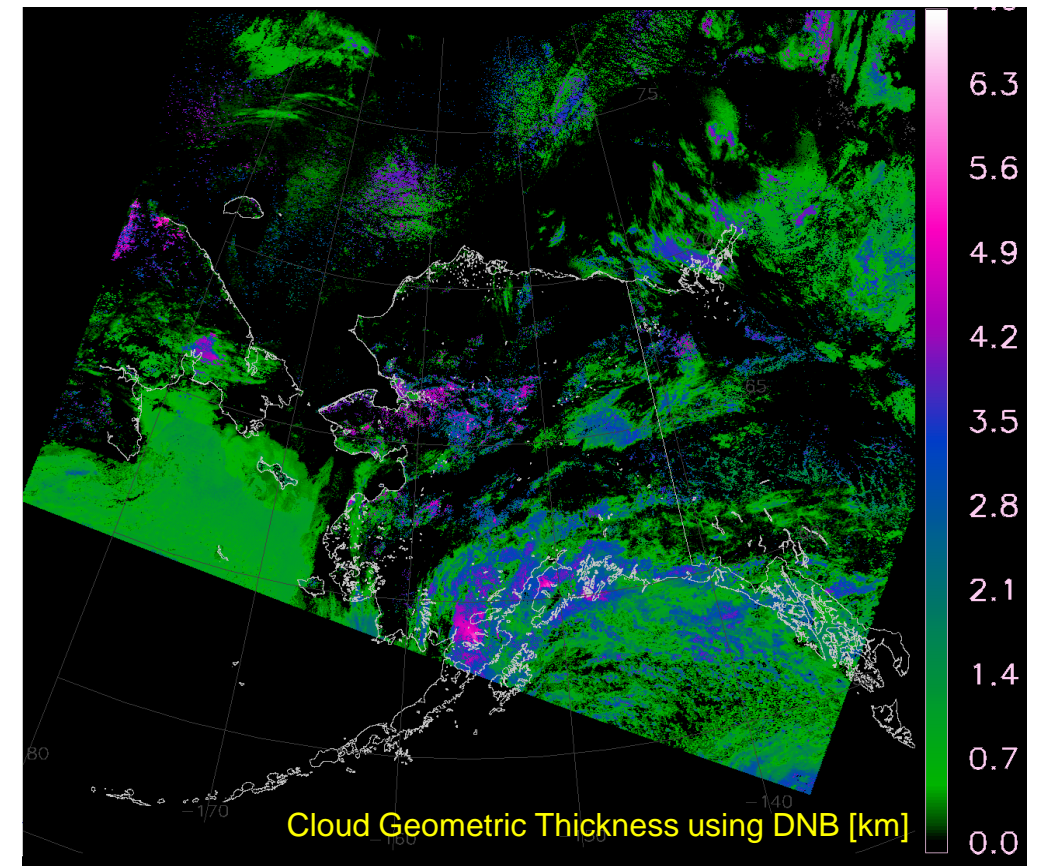
Joint Polar Satellite System (JPSS) Cloud Products and Applications in Aviation

Yoo-Jeong Noh
(CIRA/Colorado State University)

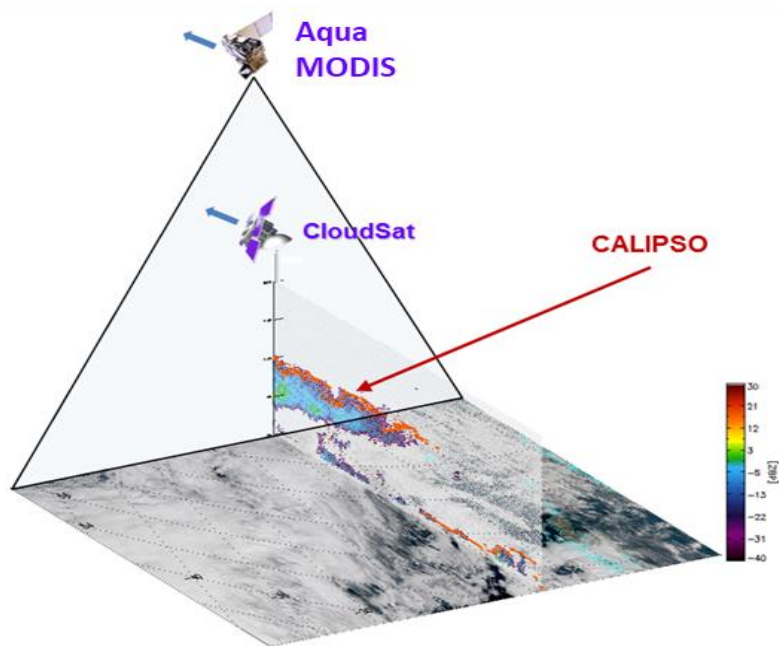
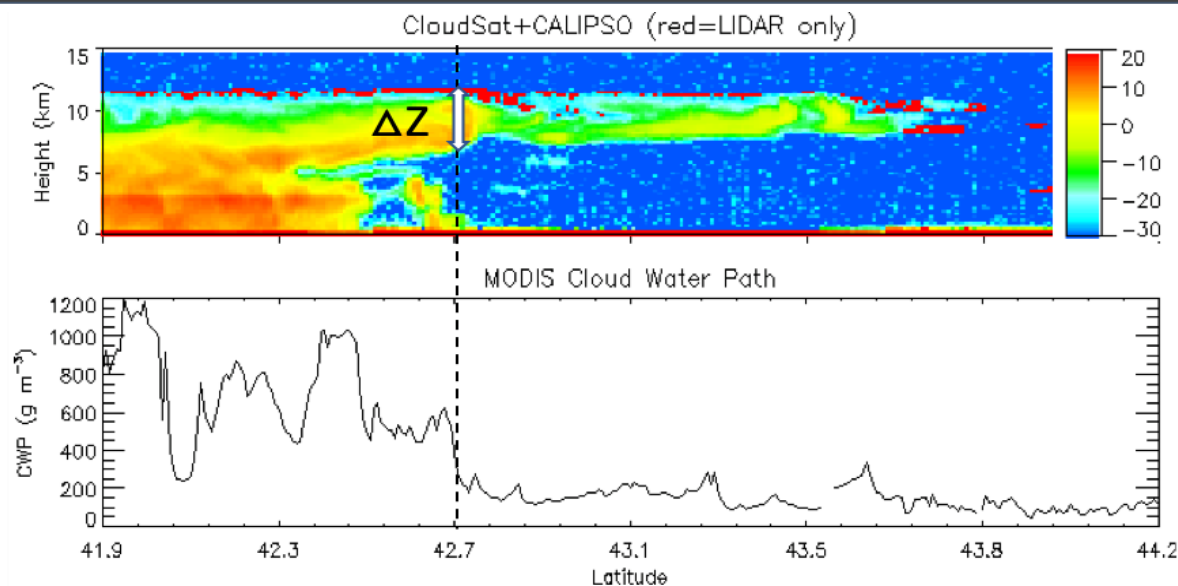
Jeff Weinrich *(NWS/OSTI, former JPSS Aviation Initiative Lead)*
John Haynes, Mattie Niznik, Steve Miller, Curtis Seaman *(CIRA)*
with NOAA and CIMSS collaborators

Thanks to our collaborators and Alaska users: Mark Kulie (NOAA), William Straka, Yue Li, Steve Wanzong (CIMSS), Tom George (Aircraft Owners & Pilots Association), Adam White (Alaska Airmen Assoc.), Becca Mazur (Arctic Testbed), Carl Dierking, Jen Delamere, Jay Cable (CICOES/GINA), Amanda Terborg, Ty Higginbotham (AWC/AWT), Nadia Smith, Rebekah Esmaili (STCNET), Jenny Colavito (FAA)

- **3-D cloud structure information** is significant to both aviation and model communities, but still challenging to conventional satellite observations using passive radiometers (e.g., VIIRS and ABI)
- Developed a statistical algorithm for Cloud Base Height (CBH) and Cloud Cover-Layers (CCL) using NASA A-Train satellite data, which is a key component to build the 3-D cloud field
- Product improvements based on user feedback to provide a comprehensive package of satellite cloud products in a more user-friendly way



Cloud Base Height Algorithm



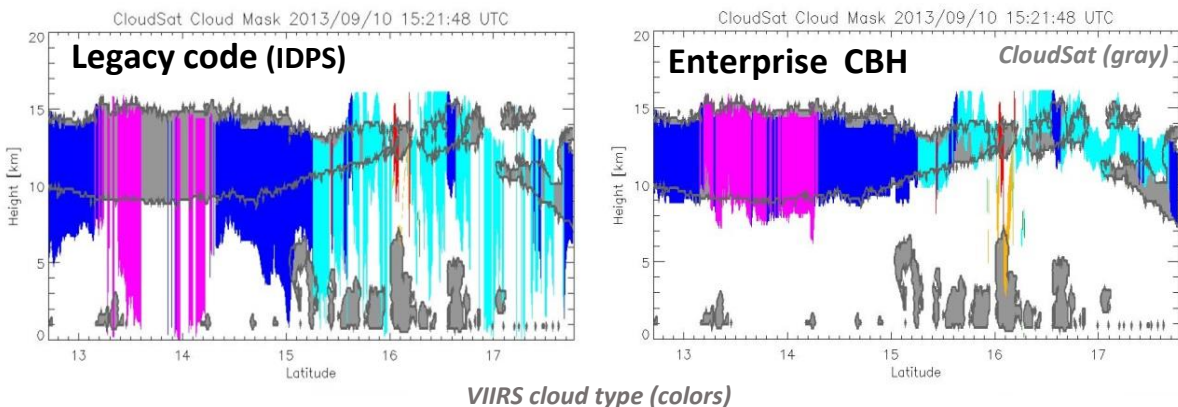
- Developed a CBH/CGT algorithm constrained by Cloud Top Height (CTH) and Cloud Water Path (CWP) using a statistical analysis of A-Train satellite data (Noh et al. and Seaman et al. 2017 JTECH)

$$CBH = CTH - \Delta Z \text{ (CGT; Cloud Geometric Thickness)}$$

where $CGT = a(CWP) + b$ (a, b based on A-Train data)

- Key component for 3-D cloud structure information, used for improved Cloud Cover/Layers (CCL)
- Operational as part of the NOAA Enterprise Cloud Algorithm
 - ✓ Operational for JPSS VIIRS and under test for GOES ABI
 - ✓ Optimal for single layer clouds

Cloud Base Height Algorithm



VIIRS cloud type (colors)



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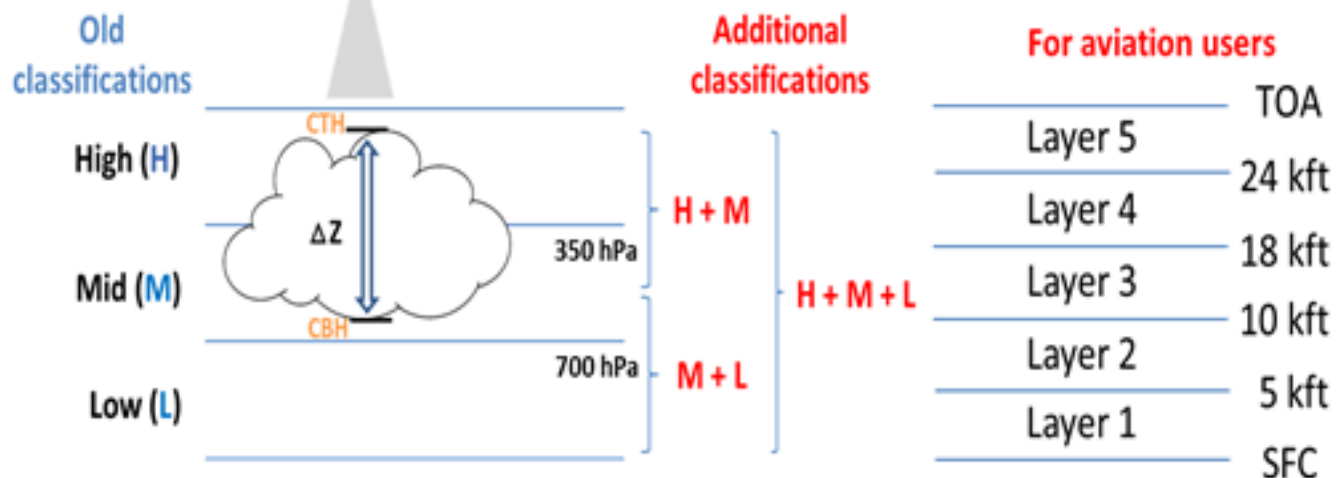
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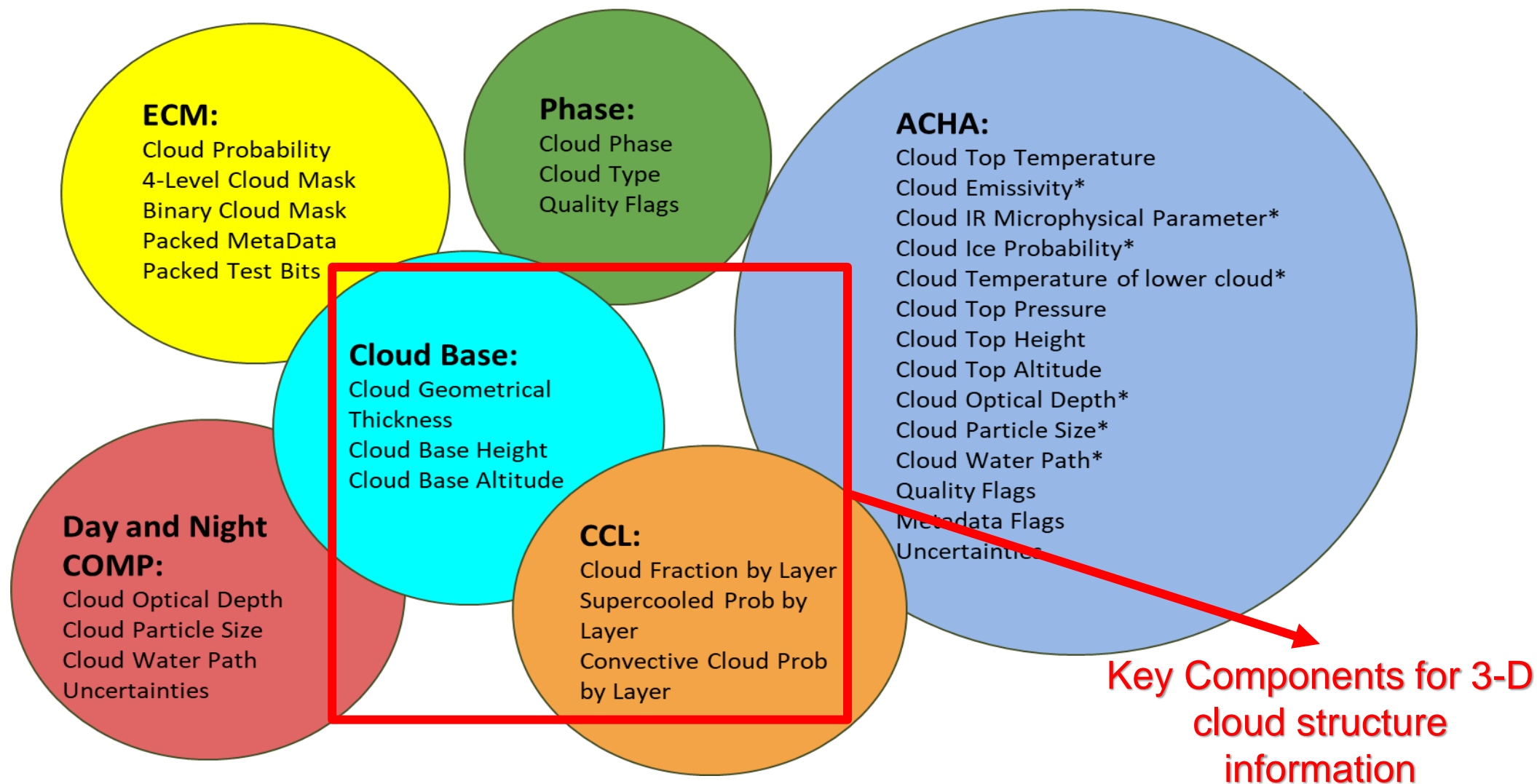
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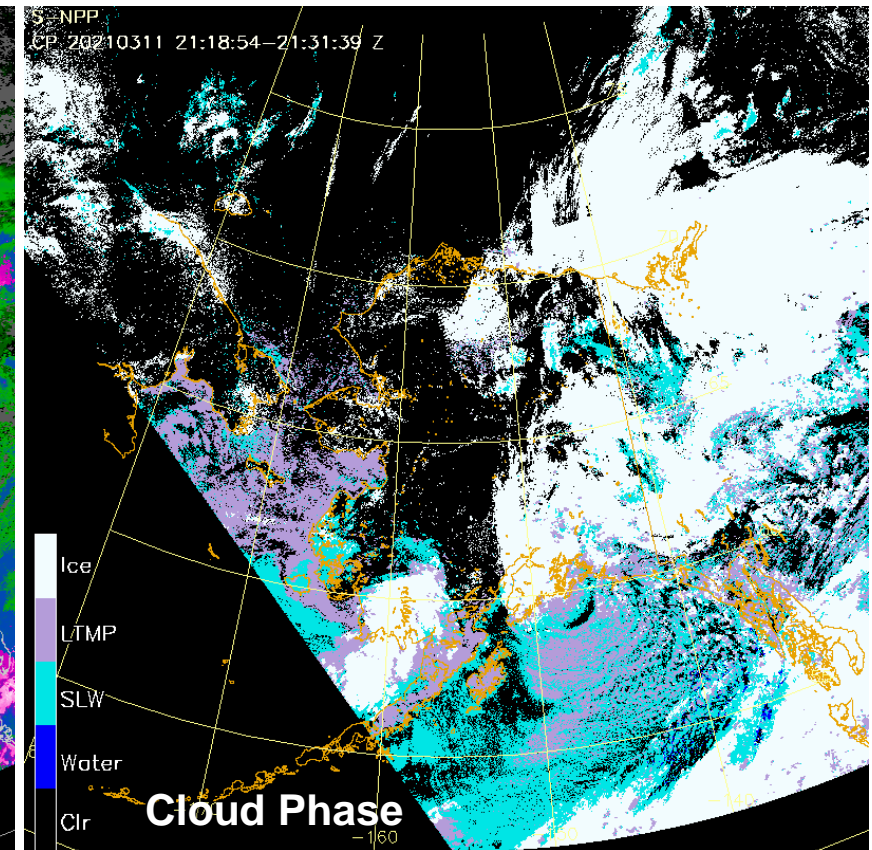
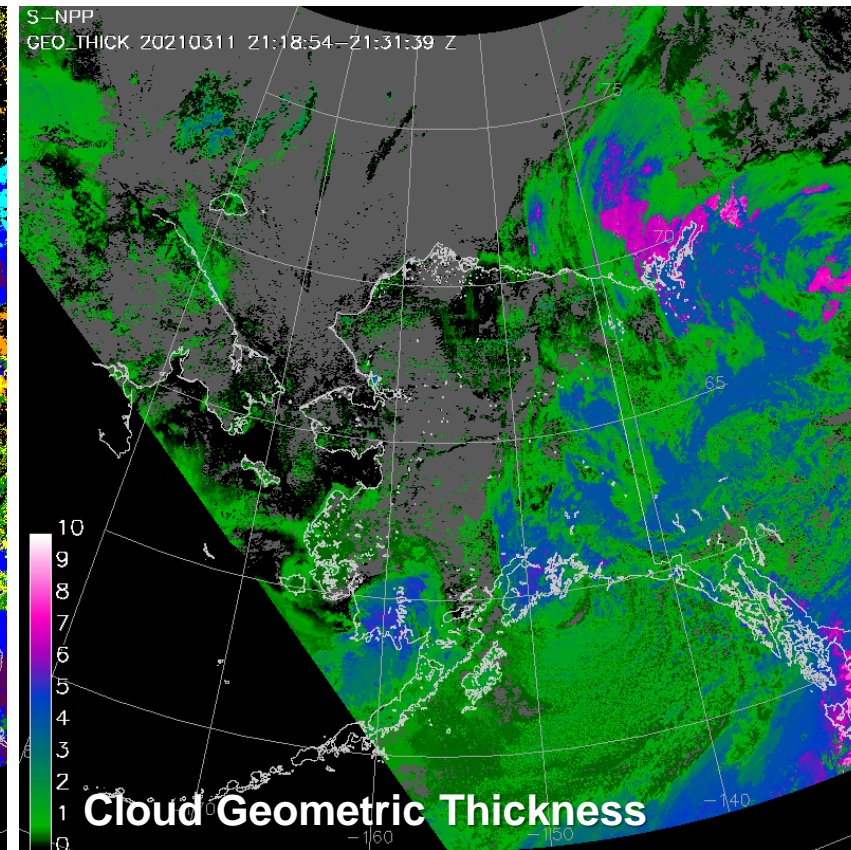
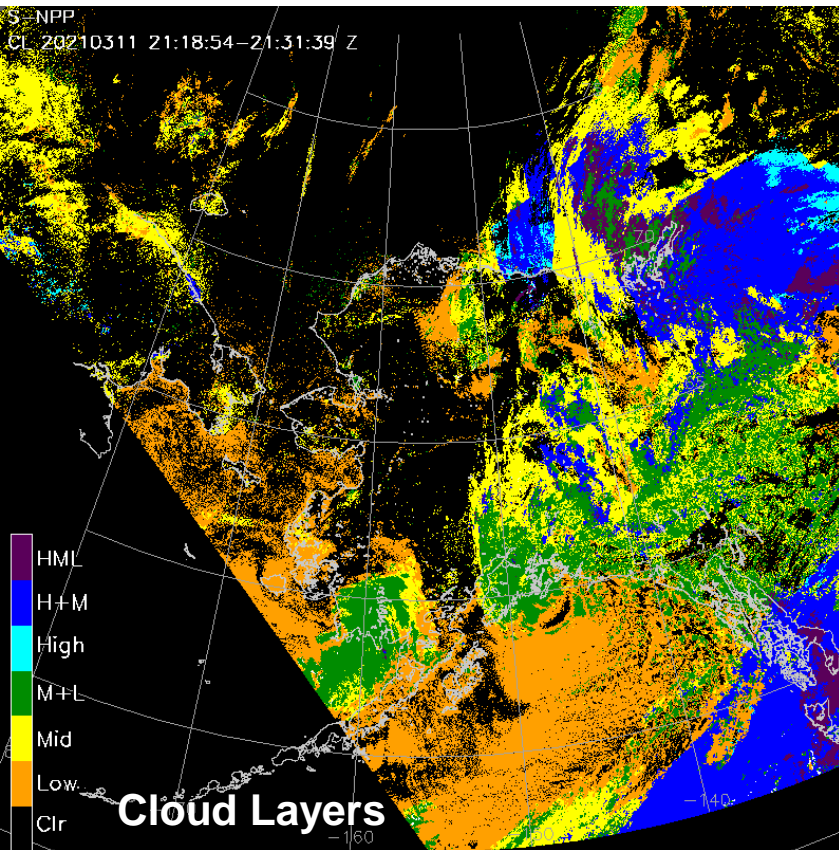


NOAA Enterprise Cloud Products



Enterprise Cloud Product Package

From 2020 EPS-SG STAR Product Requirements Review by A. Heidinger



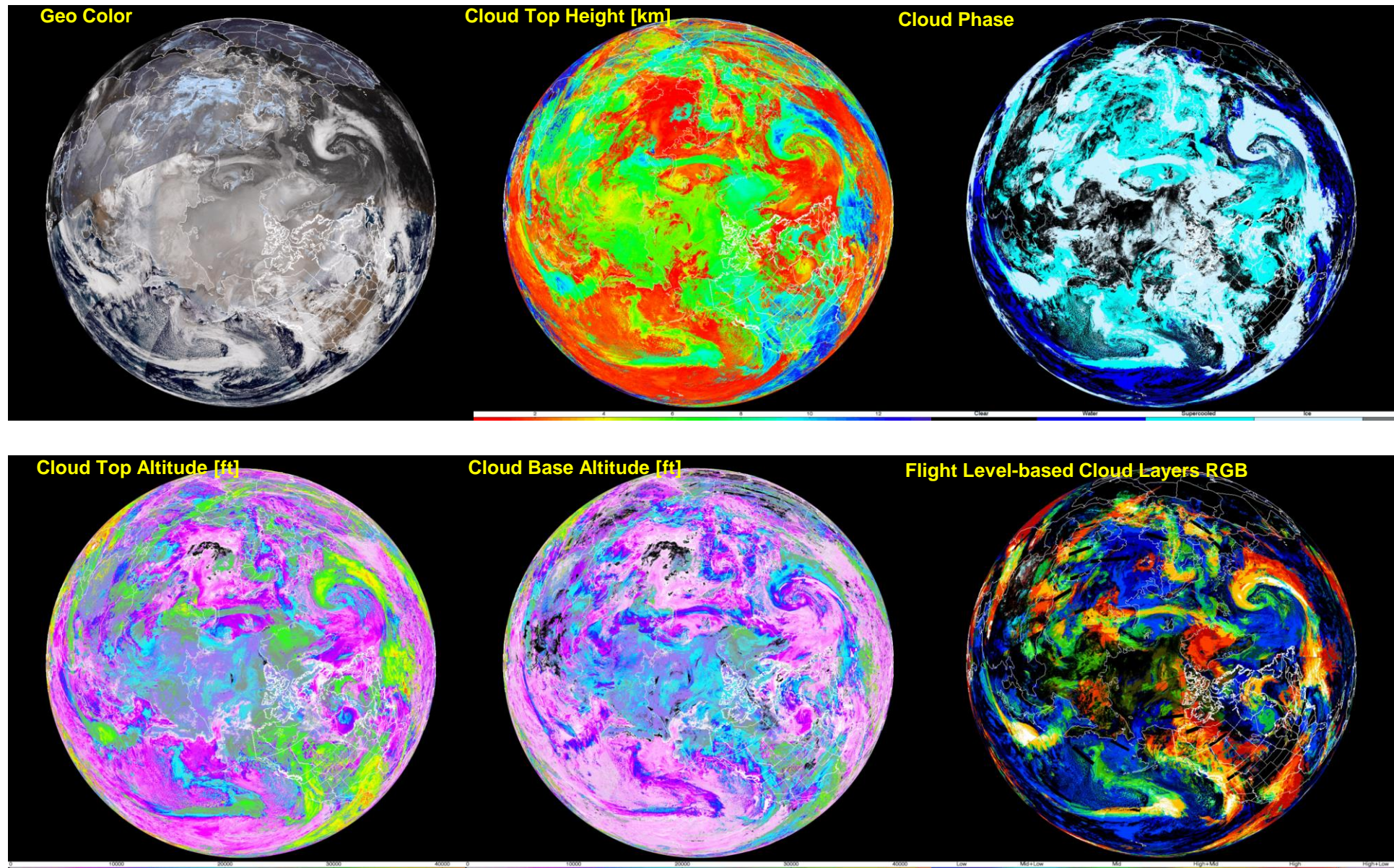
CIRA VIIRS Imagery and cloud products: https://rammb.cira.colostate.edu/ramsd/online/npp_viirs_arctic.asp

Another VIIRS site by GINA/U. of Alaska-Fairbanks: <http://hippy.gina.alaska.edu/distro/aviation/>



CIRA's Polar Slider (Northern/Southern Hemispheres)

- JPSS VIIRS Imagery and Cloud Products at <http://rammb-slider.cira.colostate.edu> (Satellite "JPSS")

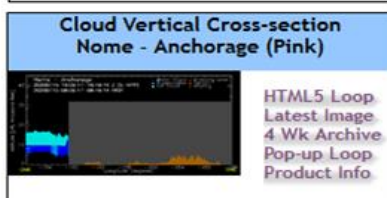
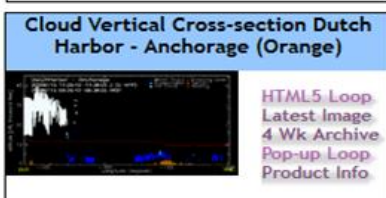
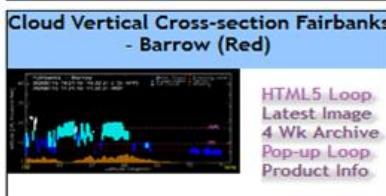
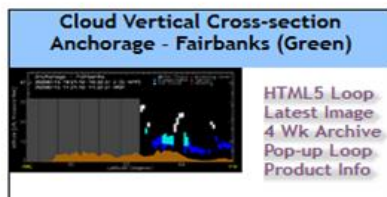
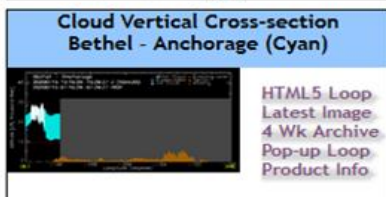
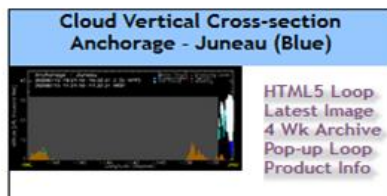


Experimental Aviation Cross-section Product

Alaska - Satellite Aviation Products

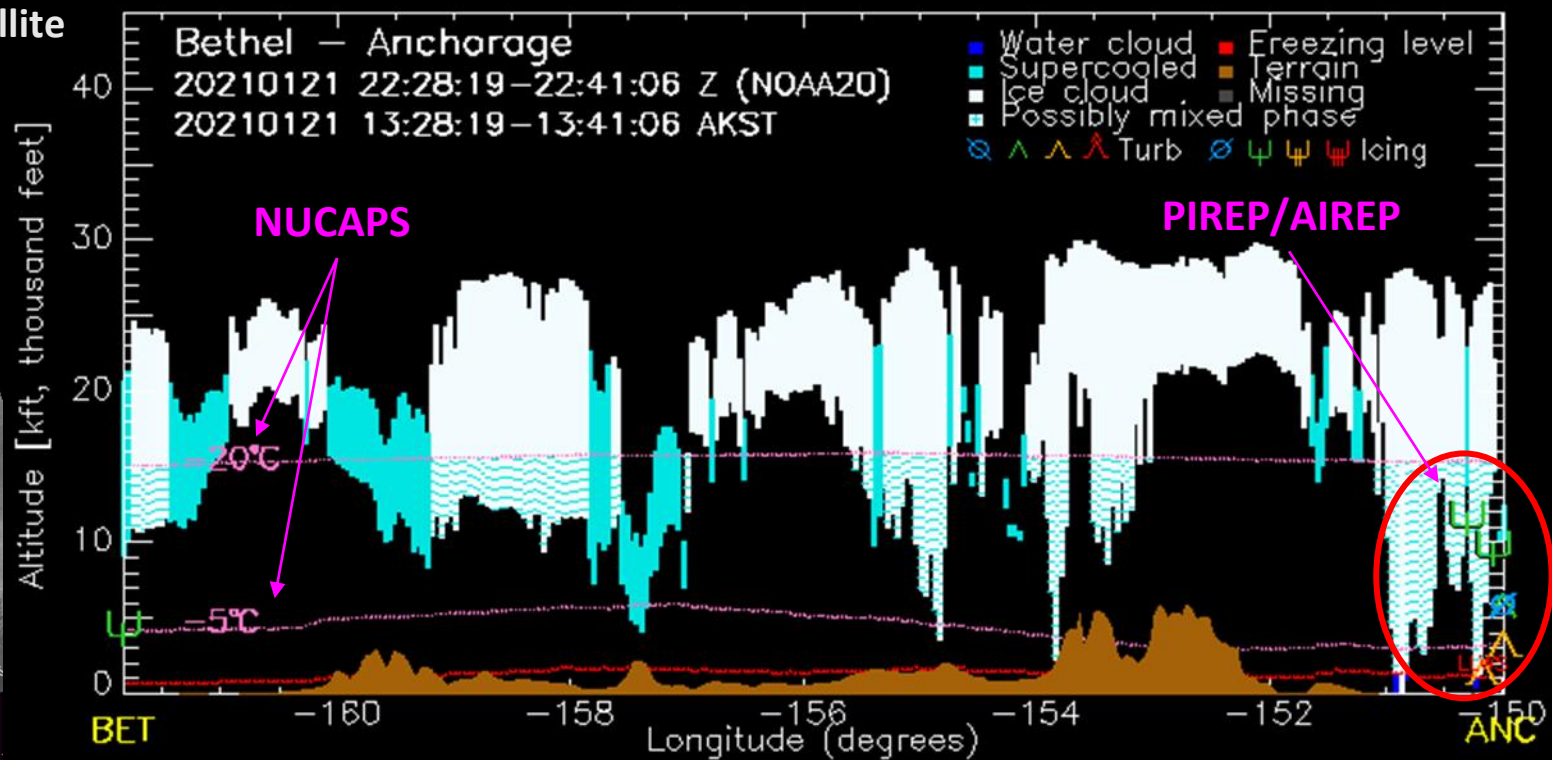
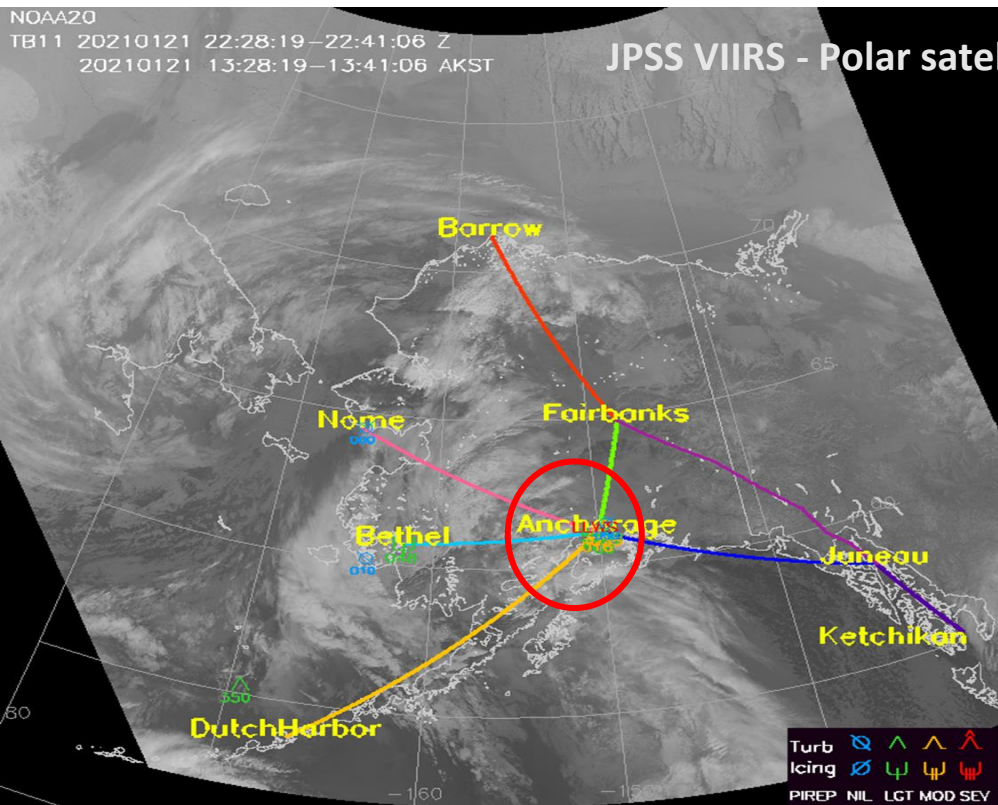
Please note our [Experimental Products Disclaimer](#) when viewing these or any other RAMMB products.
Click [here](#) for VIIRS images from the GINA Alaska Direct Broadcast.

- [Introduction-FAQ](#)
- [Quick Guide](#)
- [Feedback](#)

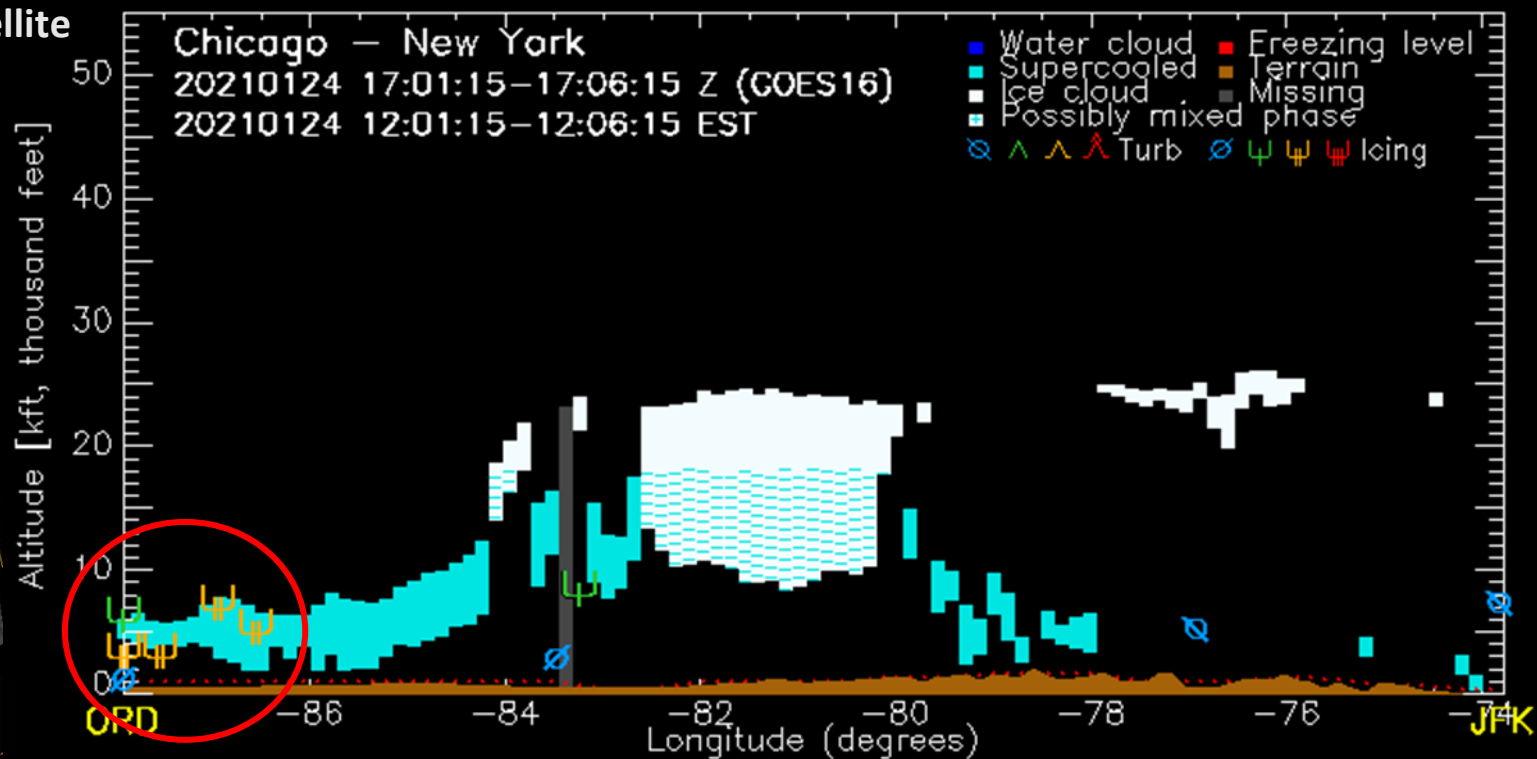
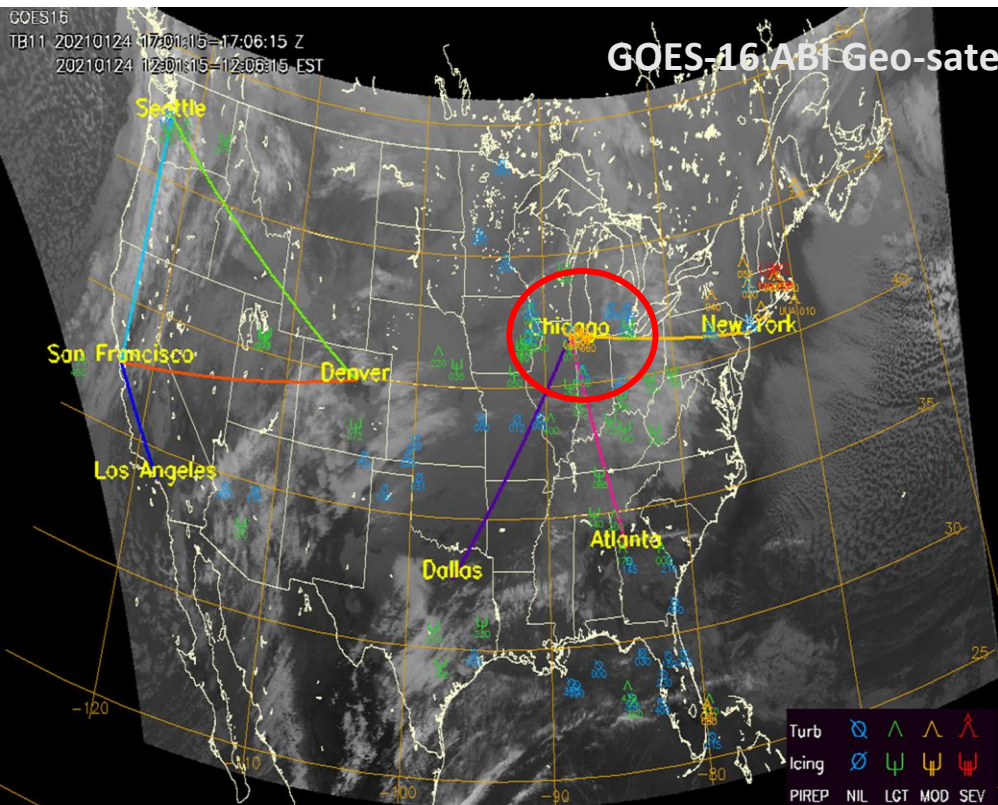


- **Experimental products for aviation users**
 - ✓ JPSS Cloud Product Alaska Demonstration as part of the NOAA JPSS Aviation Initiative
- **Cloud Vertical Cross-sections (CVC) along flight routes from NOAA Enterprise Cloud Products**
 - ✓ Satellite Cloud Top/Base Heights and Phase
 - ✓ NWP/NUCAPS temperatures data
 - ✓ PIREPs (icing and turbulence)
- **Training/display tools based on user feedback**
- **Thanks to Alaska users and collaborators!**
 - Tom George (AOPA), Adam White (AK Airmen Assoc.), Becca Mazur (Arctic Testbed), Jenny Colavito (FAA), and many users

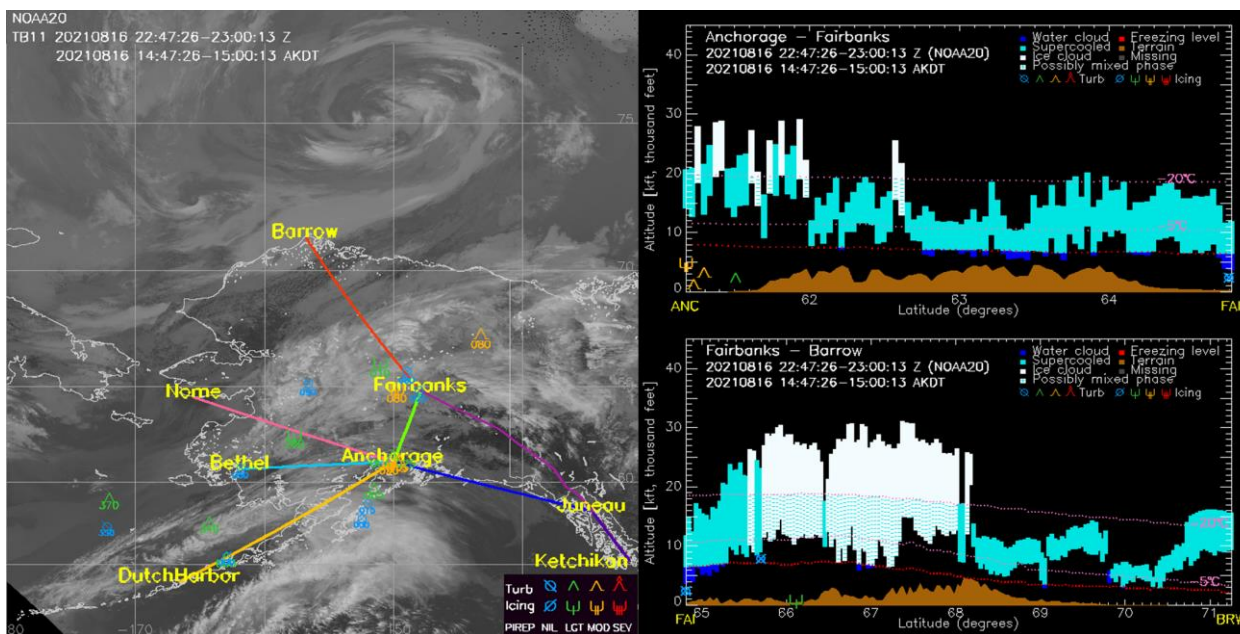
- Experimental satellite cloud products for aviation users (AK, CONUS)
 - http://rammb.cira.colostate.edu/ramsdis/online/npp_viirs_arctic_aviation.asp
 - http://rammb.cira.colostate.edu/ramsdis/online/npp_viirs_conus_aviation.asp



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- JPSS Alaska Cloud Product Demonstration/JPSS Aviation Initiative
- CIRA Polar SLIDER and VIIRS Cloud Vertical Cross-sections were used during the official cloud product demonstration for user feedback
- @NOAASatellites twitter to promote NOAA's new "Proving Ground Website" , Alaska users' blogs
- NOAA/NASA online articles, Aircraft Owners & Pilots Association (AOPA) *ePilot* newsletter and weekly video program "AOPA Live" for Alaska pilots



NOAA-20 VIIRS IR image and cloud vertical cross-sections which were provided to the National Transportation Safety Board (NTSB) for an aircraft accident case investigation. The accident occurred around 2251 UTC on 16 August 2021 near Fairbanks, Alaska. A small airbus (Cessna 208B Grand Caravan) declared an emergency due to flight control issues from serious damage to the right aileron after encountering severe turbulence. Eight passengers and one pilot on board, and luckily no injuries were reported.

JPSS VIIRS Cloud Base Height Quick Guide

Why is the Cloud Base Height (CBH) Important?

The CBH is an estimation of the base altitude of the uppermost cloud layer in each column of the atmosphere as viewed from above by satellite. Information of 3-D cloud structure is significant to the aviation community. It also bears high relevance to model developers for weather and climate applications. CBH is a key component required to construct a full 3-D cloud field, although assigning cloud base from satellite data is still challenging. The current CBH algorithm is operational as part of the NOAA Enterprise Cloud Algorithms.

Infrared (IR) 10.76µm **Cloud Base Height [km]**

Sample VIIRS IR (10.76 µm) and VIIRS Cloud Base Height from S-NPP over Alaska at 2203 UTC, 28 July 2018. Note to aviation users: CBH is also displayed in kilofeet [kft] for aviation purposes. The height in kilometer [km] is converted to pressure and next to kilofeet using a polynomial fit.

How is the VIIRS CBH Created?

The CBH is obtained from a semi-empirical approach, based on a statistical analysis of multiple satellite data (CloudSat/CALIPSO and Aqua MODIS). In the algorithm, Cloud Geometric Thickness (CGT) is derived from statistical relationships between observed CGT, Cloud Water Path (CWP), Cloud Top Height (CTH) and subtracted from CTH to generate CBH. The algorithm includes special accommodations for handling optically thin cirrus (an extinction method) and deep convection (supplementary NWP data). The CBH product is provided for any cloudy pixel with valid cloud top height globally, day and night (750 m resolution, ~50 min revisit between S-NPP and NOAA-20).

$$CBH = CTH - CGT \text{ and } CGT = (a * CWP) + b, \text{ where } a \text{ and } b \text{ are obtained from statistical relationships.}$$

Impact on Operations

Applications:

Cloud product improvement: CBH information can be used to improve the Cloud Cover Layers (CCL) products by introducing additional cloud coverage at lower levels of the profile, typically hidden under cloud top.

Aviation: Vertical cloud structures including CBH provide useful information for aviation weather applications.

NWP models: The CBH algorithm is also applicable to geostationary sensors as well as polar satellite sensors. Global observations of 3-D cloud fields are relevant to model developers for integrating improved cloud radiative feedbacks in numerical models.

Limitations

Nighttime observations: The nighttime CBH retrieval performance would be degraded due to the difficulty of CWP retrievals.

Dependency on cloud optical properties: The performance of the CBH retrieval is highly dependent on the accuracy of CTH and CWP.

Multi-layer clouds: The algorithm is optimal for single layer clouds. Most likely CBH = actual ceiling in cases an optically thin cirrus cloud, a boundary layer cloud, and deep convection but may not be 'ceiling' for multi-layered cloudy scenes. The accuracy of the CBH product for multi-layer clouds may comprise the uncertainties of the upstream retrievals.

Contributor: Y. J. Noh, Steve Miller, J. Torres (CIRA/Colorado State University) <https://www.cira.colostate.edu>

JPSS VIIRS Cloud Base Height Quick Guide

Cloud Top Height [kft] **Cloud Base Height [kft]**

Cloud Top Height and VIIRS Cloud Base Height displayed in kilofeet [kft] for aviation users (S-NPP VIIRS at 2122 UTC, 18 February 2019). Cloud products over Alaska are viewable on the GINA Website (<http://hippy.gina.alaska.edu/distro/aviation/>).

Applied to Cloud Cover Layers (CCL)

CBH information is used for improved CCL products, which increases lower cloud coverage hidden below cloud top.

It should be noted the algorithm is optimal for single clouds. The CBH (and low CCL) may not be the lowest for multi-layered cloudy scenes when thick top layers present. The nighttime performance would be degraded.

Layer	TOA
Layer 5	24 kft
Layer 4	18 kft
Layer 3	10 kft
Layer 2	5 kft
Layer 1	SFC

CBH in Polar SLIDER

CIRA's Polar SLIDER for VIIRS imagery & cloud products at <http://rammb-slider.cira.colostate.edu> (Satellite "JPSS")

Development of a statistical cloud base height retrieval algorithm: Noh et al., 2017, J. Atmos. Ocean. Tech., 34(3), 585-598.

Contributor: Y. J. Noh, Steve Miller, J. Torres (CIRA/Colorado State University) <https://www.cira.colostate.edu>

JPSS Satellite Cloud Vertical Cross-section (CVC) Quick Guide

What is the CVC Product?

This experimental product is part of a 3-D satellite cloud height field that displays where clouds are present in a vertical column of the atmosphere. Information on the 3-D cloud structure is important to the aviation community, used for flight planning. Derived from the Visible Infrared Imaging Radiometer Suite (VIIRS) instrument on-board operational NOAA satellites, the CVC is computed along flight routes from Cloud Top Height (CTH) and Cloud Base Height (CBH) products. Determining the cloud base from satellites is challenging due to inherited limitations of passive sensors (e.g. VIIRS) which primarily detect cloud top or vertically integrated features.

How is CVC Created?

The CVC product is generated by extracting information from several sources, which are combined and displayed along defined routes. The product incorporates CTH data (derived from multiple infrared wavelength observations) along with an estimate of CBH, and is categorized by cloud top phase (also from infrared observations). Possibly mixed or water phase at lower levels are also indicated using temperature data. A statistical approach is used to estimate cloud base with input from cloud top and water products, based on multiple satellite sources including radar and lidar sensors. When satellite input data is not available, a numerical weather model value is used as supplementary data. This processing sequence is currently being applied to VIIRS sensors onboard the S-NPP and NOAA20 satellites, which have a ~50 minute revisit time between the two.

Thermal IR satellite image over Alaska and CVC varying in altitude from two flight routes. CVC displayed in thousand feet [kft] for aviation purposes and colored by cloud top phase: water (blue), supercooled water (cyan), ice (white), missing data (gray), and possibly mixed at lower levels (pink+yellow). Freezing levels (red) with PIREPs (turb/icing) are also included. Access imagery: http://rammb.cira.colostate.edu/ramdis/online/npp_viirs_arctic_aviation.asp

Impact on Operations

Applications:

Aviation: Vertical cloud structures from satellite data (applicable to both polar and geostationary sensors) provide information for aviation weather applications globally in combination with numerical weather models.

3-D cloud product improvement: CTH and CBH information is used to compute the CVC and other Cloud Cover Layers (CCL) products. CBH introduces additional cloud coverage at lower levels, typically hidden under cloud top.

Limitations

Dependency on cloud optical properties: The cross-section product relies on inputs from both cloud top and base products. CBH performance is highly dependent on the accuracy of cloud top and water path data. Missing values are displayed on the product if suitable data is not available.

Multi-layer clouds: The algorithm is optimal for single layer clouds such as thin cirrus clouds, boundary layer clouds, and deep convection cells. It is not optimal for observations consisting of multiple cloud layers; this may limit the accuracy of the product.

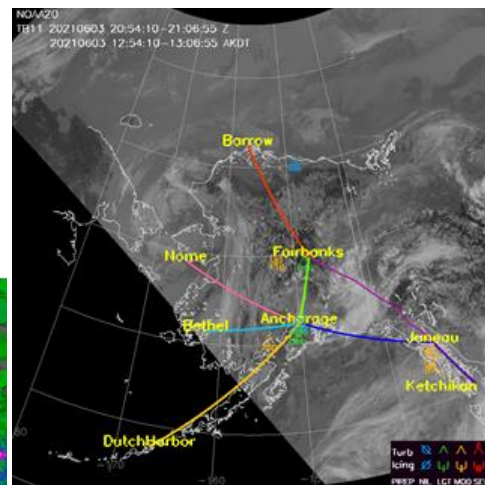
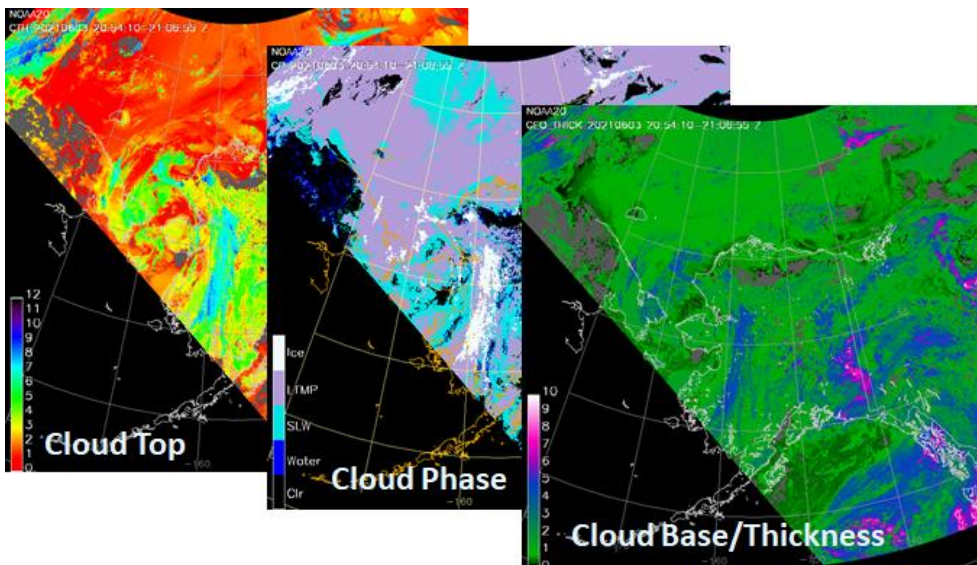
Nighttime observations: The nighttime performance would be degraded due to missing low cloud layers and the difficulty of computing cloud water content. CVC should be used with caution at night.

Resources: NOAA AWG Cloud Height Algorithm: A. Heidinger, 2015, https://www.star.nesdis.noaa.gov/jps/docs/ATBD/ATBD_EPS_Cloud_ACHA_v3.0.pdf
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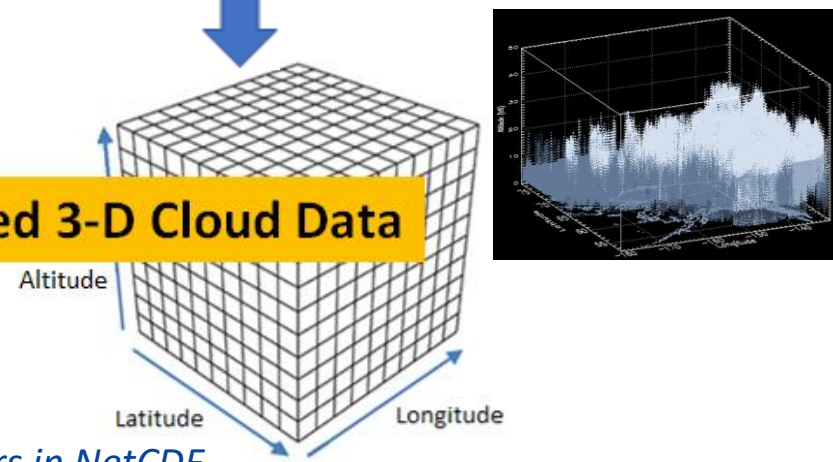
- A comprehensive package to extend the benefit of satellite data into the vertical dimension for aviation users -> **Custom Cloud Cross-sections**
- Derived from multiple cloud products (cloud top/base and phase) with temperatures (NUCAPS/NWP model), PIREPs (icing/turbulence), and terrain data

VIIRS individual 30-sec granules, pixel data



Temperatures (NUCAPS/NWP)
Terrain
PIREPs (Icing/Turb)

Gridded 3-D Cloud Data



Compact 16-bit integers in NetCDF



New Aviation Website for custom cross-sections

<https://aviation.cira.colostate.edu>

Regional and Mesoscale Meteorology Branch

Home Real-Time Data Research Projects Training/Outreach Resources

CIRA Aviation

Home **NEW! Custom Flight Path** Back to Old Site

Quick Guide | Introduction/FAQ | Experimental Products Disclaimer | Survey | Contact Us

Click on each point along your flight path to view the "Cross-Section" to

Clear All Manual Entry

Opacity

Your Flight Path and Cross-Section

© Did you know? You can bookmark this URL to save your route; it will always show the latest data when you visit!

Altitude [kft, thousand feet]

20211024 23:45:56-23:57:18 Z (S-NPP)
20211024 15:45:56-15:57:18 AKDT

- Water cloud
- Supercooled
- Ice cloud
- Possibly mixed phase
- Freezing level
- Terrain
- Missing
- Turb
- Iceing

A (PAFA)
147.86°W
64.82°N

B (PFNO)
161.02°W
66.82°N



Cloud Cover Layers with ML

- Aviation is particularly concerned with the location of **low clouds** (IFR conditions, icing, etc.) but still challenging in **multilayer scenes**
- Using Random Forest (RF) and Artificial Neural Network (ANN) - *All pixel-based*
- ABI multispectral information and NWP layer humidity trained using ‘truth’ from CloudSat radar and CALIPSO lidar
 - CloudSat/CALIPSO cloud boundaries, matched to parallax-corrected GOES-16 data from Oct 2018 – June 2019; total of 21.6 million radar profile
 - **RF**: 125 trees, max depth of 30
 - **ANN**: 3 layers fully connected layers, 37 to 71 hidden units per layer
- Allows addition of a **High + Low** classification

Variable	Description and units	Notes
REFL01 through REFL06	ABI Channel 01 through 06 visible reflectances	Normalized by $\cos(\text{solar zenith angle})$
TB07 through TB16	ABI Channel 07 through 16 brightness temperature (K)	
RH _{max}	Maximum RH between 650 and 1000 hPa (%)	
RH ₁₅₀	RH at 150 hPa (%)	
Lat	Latitude in (degrees north)	
Flag _{sfc}	0 indicates land or mix, 1=water surface	
Flag _{snow/ice}	0 indicates snow/ice free land surface, 1=snow/ice present	Set to 1 if either GFS snow depth or ice fraction are > 0

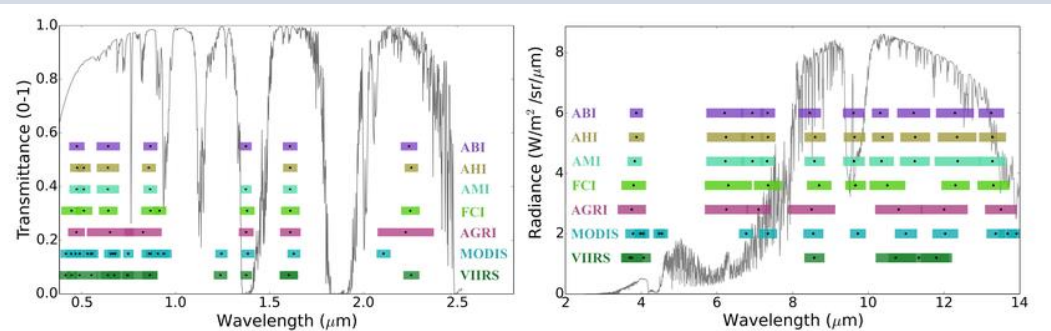
5-fold cross validation was used for hyperparameter tuning of both models; details in Haynes et al. (2021)

To nighttime

- Remove channels 1 through 7 (vis) from training
- PoD/FAR/CSI changes from (0.815 / 0.147 / 0.715) for the full algorithm to (0.770 / 0.184 / 0.656)
- Performance decrease, but still improvement over CCL

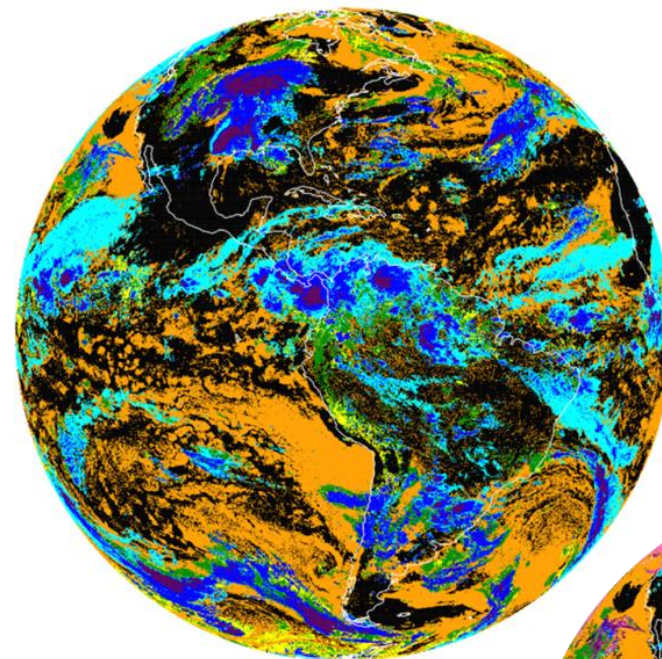
From ABI to VIIRS

- Transfer learning: we are translating the algorithm to use VIIRS inputs at similar channels



Wang et al. 2020 (CC-BY 4.0, unmodified)

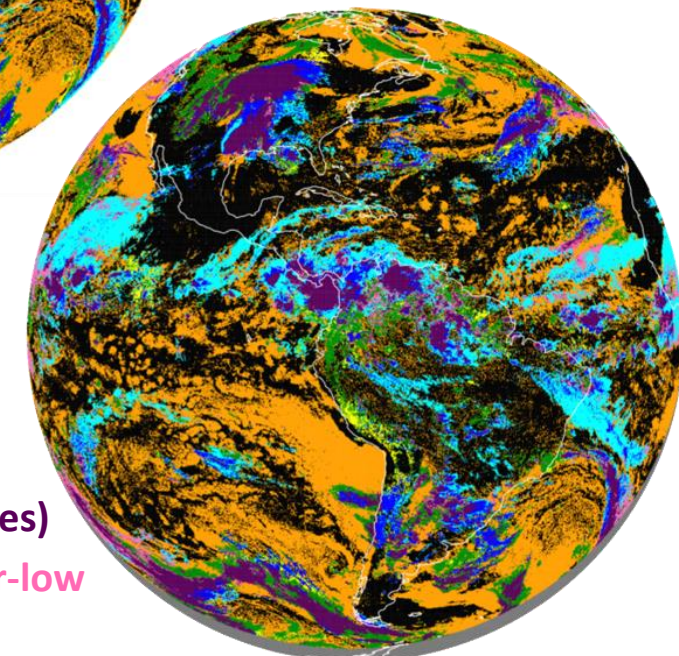
- CloudSat/CALIPSO/VIIRS matchups do occur, but the dataset is small given their orbits
- However, we can ABI/VIIRS matchups to adjust algorithm input histograms
- Future work to all vertical levels



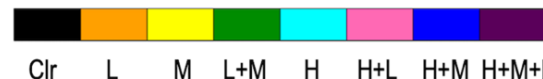
CCL supplemented by RF on global scale

Before machine learning

After machine learning

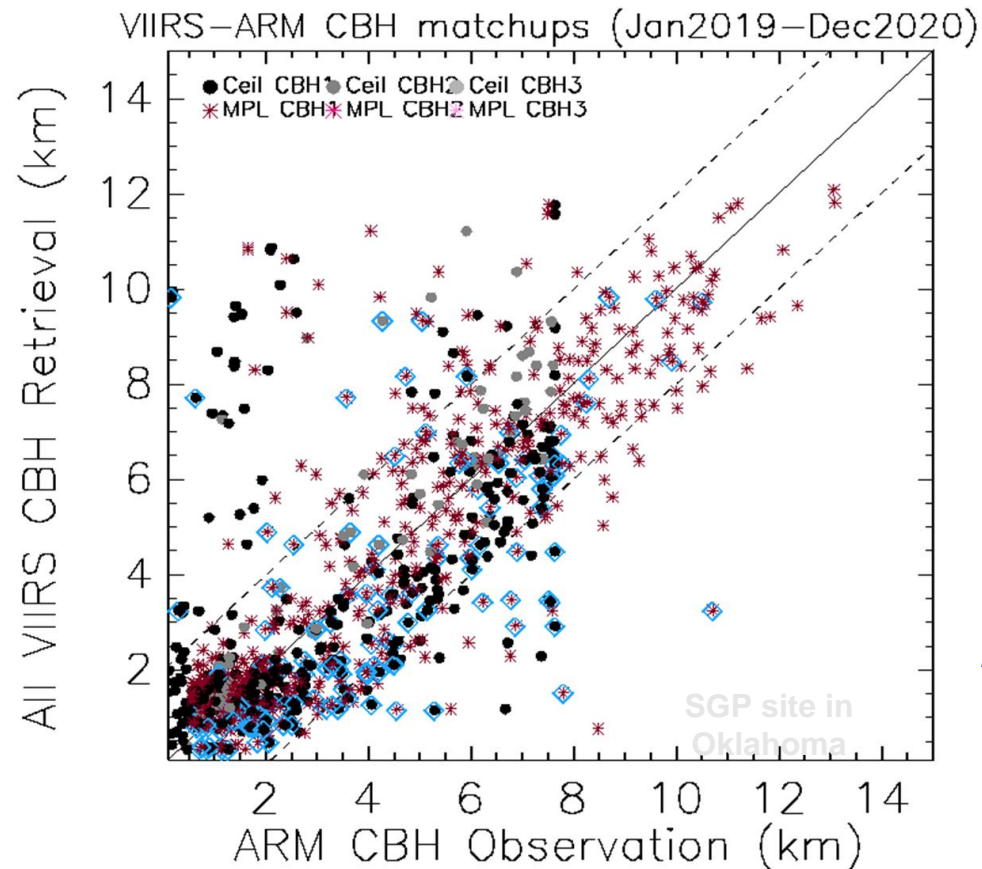
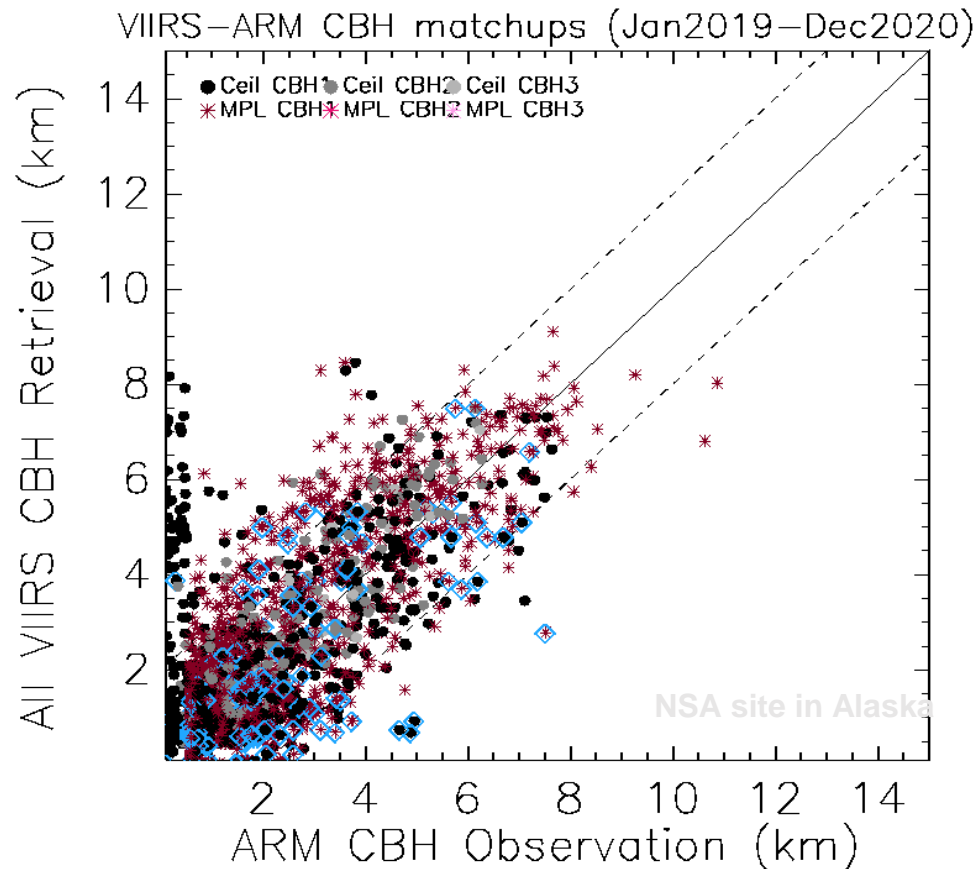


More deep clouds (purples)
Introduction of high-over-low (pinks)





CBH comparisons with ARM measurements



*In progress with
METAR data*

Comparisons of CBHs from VIIRS and ARM ground-based measurements for Jan 2019 - Dec 2020 (Micro-Pulse Lidar in red-brown asterisk and Ceilometer in black-gray circles). Collocations between VIIRS pixel (parallax-corrected) and ARM site locations were conducted within 0.1 degree and 5-min window. Note that nighttime CBHs from NLCOMP using DNB are colored in blue. (*“Within-spec” comparisons when VIIRS CTH is within 2 km against surface lidar CTH*)

- **Develop a statistical CBH algorithm to provide 3-D cloud structure information using satellite observations**
 - Operational as part of the NOAA Enterprise Cloud Algorithms
- **Improve science algorithms**
 - Machine learning approach to improve multilayer cloud retrievals
 - Utilizing VIIRS DNB for nighttime retrievals (+ NWP, ATMS)
 - Validation against surface-based measurements and spaceborne active sensors
- **Introduce **Cloud Vertical Cross-section products for aviation users****
- **Construct fully gridded **3-D Cloud data****
- **Product demonstration and training tools based on user feedback**

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